Vector[™] VS330 GNSS Compass

Professional Heading and Positioning Receiver

- Extremely accurate heading with baselines up 50 m
- Dual frequency GPS/GLONASS/BeiDou RTK capable
- L-Band and Beacon capable
- Automatic Antenna Baseline Survey
- Maintain heading and position lock when more of the sky is blocked
- RTK, Atlas L-Band DGNSS, Beacon and SBAS capable
- Runs Athena core GNSS engine offering improved initialization times, robustness in difficult environments, performance over long baselines and under scintillation
- Integrated gyro and tilt sensors help deliver fast start-up times and provide heading updates during temporary loss of satellites



Experience the Vector™ VS330 with our powerful Athena™ GNSS core engine technology. Developed for precise marine, dynamic positioning, and land applications requiring precise heading and RTK position performance.

The Vector VS330 utilizes all of the innovations in Hemisphere GNSS' Eclipse™ Vector technology. Our optimized Eclipse Vector technology brings a series of new features to the Vector VS330 including heave, pitch, and roll output, and more robust heading and positioning performance.

The Vector VS330 receiver, with its display and user interface, can be conveniently installed near the operator. The two antennas are mounted separately and with a user-determined separation to meet the desired heading accuracy. The Vector VS330 uses Atlas L-Band, Beacon and SBAS for differential positioning. Our firmware allows the VS330 to smoothly transition between DGNSS systems.



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Vector™ VS330 GNSS Compass

GNSS Sensor Specifications

 Receiver Type:
 Vector GNSS L1/L2 RTK Receiver

 Signals Received:
 GPS, GLONASS, BeiDou, and Atlas

 Channels:
 540

 GPS Sensitivity:
 -142 dBm

 SBAS Tracking:
 3-channel, parallel tracking

 Update Rate:
 10 Hz standard, 20 Hz optional

1.2 m

Positioning Accuracy RMS: Horizontal

RMS: Single Point ¹: SBAS (WAAS) ²: Atlas L-Band ³: Code Differential GNSS ¹: RTK ².⁴: Heading Accuracy:

 0.3 m
 0.6 m

 0.1 m
 0.2 m

 0.3 m
 0.6 m

 10 mm + 1 ppm
 20 mm + 2 ppm

 0.17* rms @ 0.5 m antenna separation
 0.09* rms @ 1.0 m antenna separation

 0.04* rms @ 2.0 m antenna separation
 0.02* rms @ 5.0 m antenna separation

 0.02* rms @ 10.0 m antenna separation
 0.01* rms @ 10.0 m antenna separation

Vertical

2.5 m

Pitch/Roll Accuracy (RMS): 1° Heave Accuracy (RMS): Timing (1PPS) Accuracy: 20 ns Rate of Turn: Compass Safe Distance: Cold Start: Warm Start: Hot Start: Heading Fix: Maximum Speed: Maximum Altitude: Differential Options: Athena RTK

30 cm (DGPS) ⁵,10 cm (RTK) ^{2,4} 20 ns 100°/s maximum 30 cm (with enclosure) ⁶ 60 s (no almanac or RTC) 20 s typical (almanac and RTC) 1 s typical (almanac, RTC and position) 10 s typical (valid position) 1,850 mph (979 kts) 18,288 m (60,000 ft) SBAS, Beacon, External RTCM, Atlas L-Band and

Beacon Sensor Specifications

Channels: Frequency Range: Operating Modes: Compliance: 2-channel, parallel tracking 283.5 to 325 kHz Manual, Automatic, and Database IEC 61108-4 beacon standard

L-Band Sensor Specifications

Receiver Type: Channels: Sensitivity: Channel Spacing: Satellite Selection: Reacquisition Time: Single Channel 1530 to 1560 MHz -130 dBm 5 kHz Manual or Automatic 15 sec (typical)

Communications

Serial Ports: USB Ports: Baud Rates: Correction I/O Protocol:

Data I/O Protocol: Timing Output: 2 full-duplex RS232, 1 half-duplex RS422 port 1 USB-A 4800 - 115200

RTCM SC-104, L-Dif^{™ 7}, RTCM v2 (DGPS), RTCM v3 (RTK), CMR (RTK), CMR+ (RTK) ³ NMEA 0183, Hemisphere GNSS binary ⁶ 1 PPS (CMOS, active high, rising edge sync, 10 kΩ, 10 pF load)

Authorized Distributor:

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Power Input Voltage: Power Consumption:

Current Consumption:

Power Isolation: Reverse Polarity Protection: Antenna Voltage: Antenna Short Circuit Protection: Antenna Gain Input Range: Antenna Input Impedance:

Environmental

Operating Temperature: Storage Temperature: Humidity: Mechanical Shock:

Vibration: EMC:

Enclosure:

Mechanical Dimensions:

Weight: Status Indications (LED):

Power Switch:

Power/Data Connector: Power Connector: Data Connector: Antenna Connectors:

Aiding Devices Gyro:

Tilt Sensors:

8 to 36 VDC 5.3 W nominal (GPS L1/L2 + GLONASS L1/L2) 7 W nominal (GPS L1/L2 + GLONASS L1/L2 + BeiDou B1/B2/B3 + Atlas L-Band) 0.44 A nominal (GPS L1/L2 + GLONASS L1/L2) 0.51 A nominal (GPS L1/L2 + GLONASS L1/L2 + BeiDou B1/B2/B3 + Atlas L-Band) 500 V Yes 5 VDC maximum 60mA

Yes 10 to 40 dB 50 Ω

-30°C to + 70°C (-22°F to + 158°F) -40°C to + 85°C (-40°F to + 185°F) 95% non-condensing EP455 Section 5.14.1 Operational (when mounted in an enclosure with screw mounting holes utilized) EP455 Section 5.15.1 Random CE (IEC 60945 Emissions and Immunity) FCC Part 15, Subpart B CISPR22 IP66 (IEC 60529)

20.2 L x 12.0 W x 7.5 H (cm) 8.0 L x 4.7 W x3.0 H (in) ~1.1 kg (~2.5 lbs.) Power, Primary and Secondary GPS lock, Differential lock, DGPS position, Heading, RTK lock, L-Band DGNSS lock Front panel soft switch 9-pin ODU metal circular 2-pin ODU metal circular DB9 (sealed) 2 TNC (female)

Provides heading smoothing with GNSS. Drift rate is 1° per minute in heading for periods up to 3 minute when loss of GNSS has occurred ⁴ Provide pitch, roll data, assist in fast start-up and heading reacquisition

1 Depends on multipath environment, number of satellites in view, satellite geometry, no SA, and ionospheric activity.

- 2 Depends on multipath environment, number of satellites in view, satellite geometry, no SA, and ionospheric activity.
- 3 Requires a subscription
- 4 Depends on multipath environment, number of satellites in view, satellite geometry, baseline length (for differential services), and ionospheric activity.
- 5 Based on a 40 second time constant
- 6 This is the minimum safe distance measured when the product is placed in the vicinity of the steering magnetic compass. The ISO 694 defines "vicinity" relative to the compass as within 5 m (16.4 ft) separation.
 7 Hemisphere GNSS proprietary

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